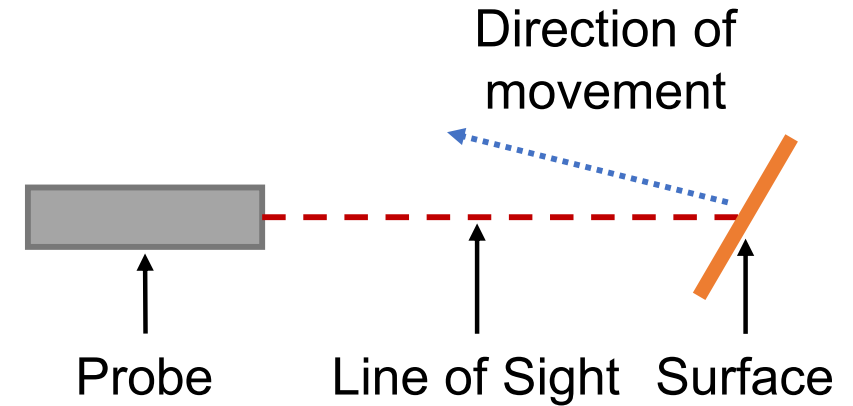


Broadband Laser Ranging development

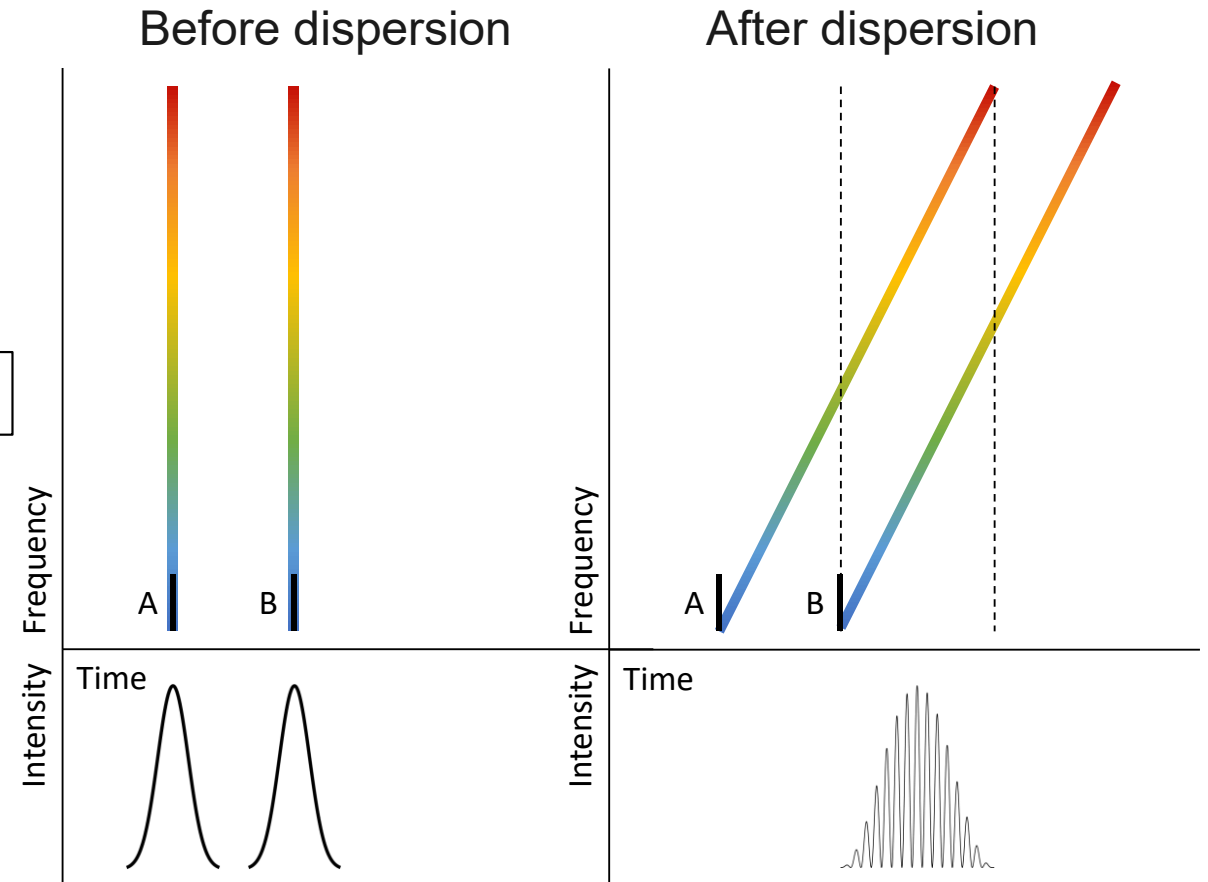
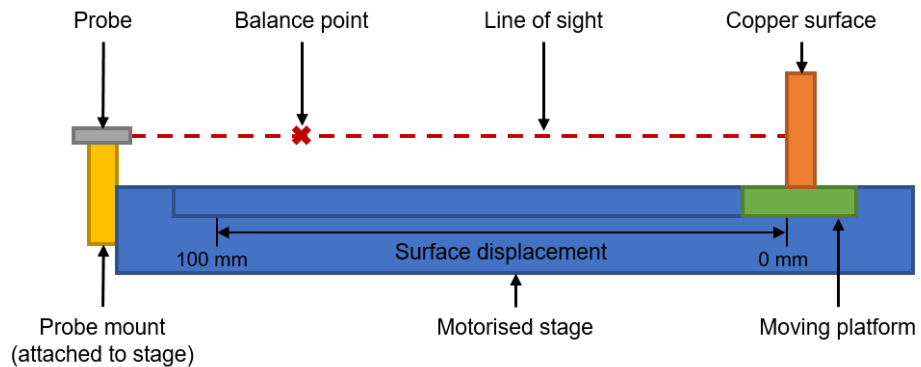
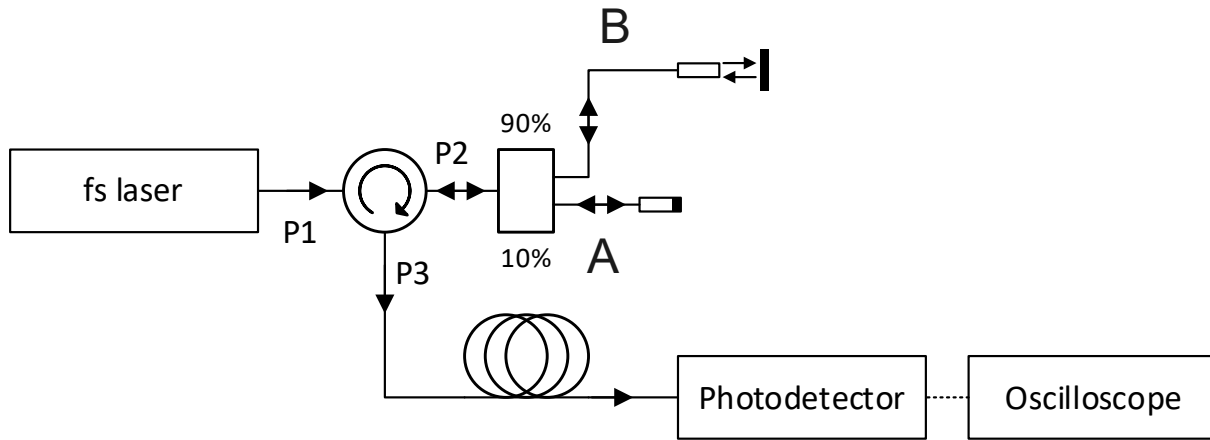
Callum Pryer

BLR at AWE



- Need ranging because of movement not along the line of sight of probe which integrating HetV cannot record
- Previously investigating ranging techniques and BLR was selected to develop further
- Prototype single channel BLR system built
- Complicated to set up and field, needed improvements for reliable and quicker setup but demonstrated technique
- Last couple of years, doubled the number of BLR channels available and made many improvements for both hardware and software
- Static lab testing showed an overall weighted mean and uncertainty 0.00 ± 0.02 mm between BLR and LUNA measured displacements of a surface

BLR introduction

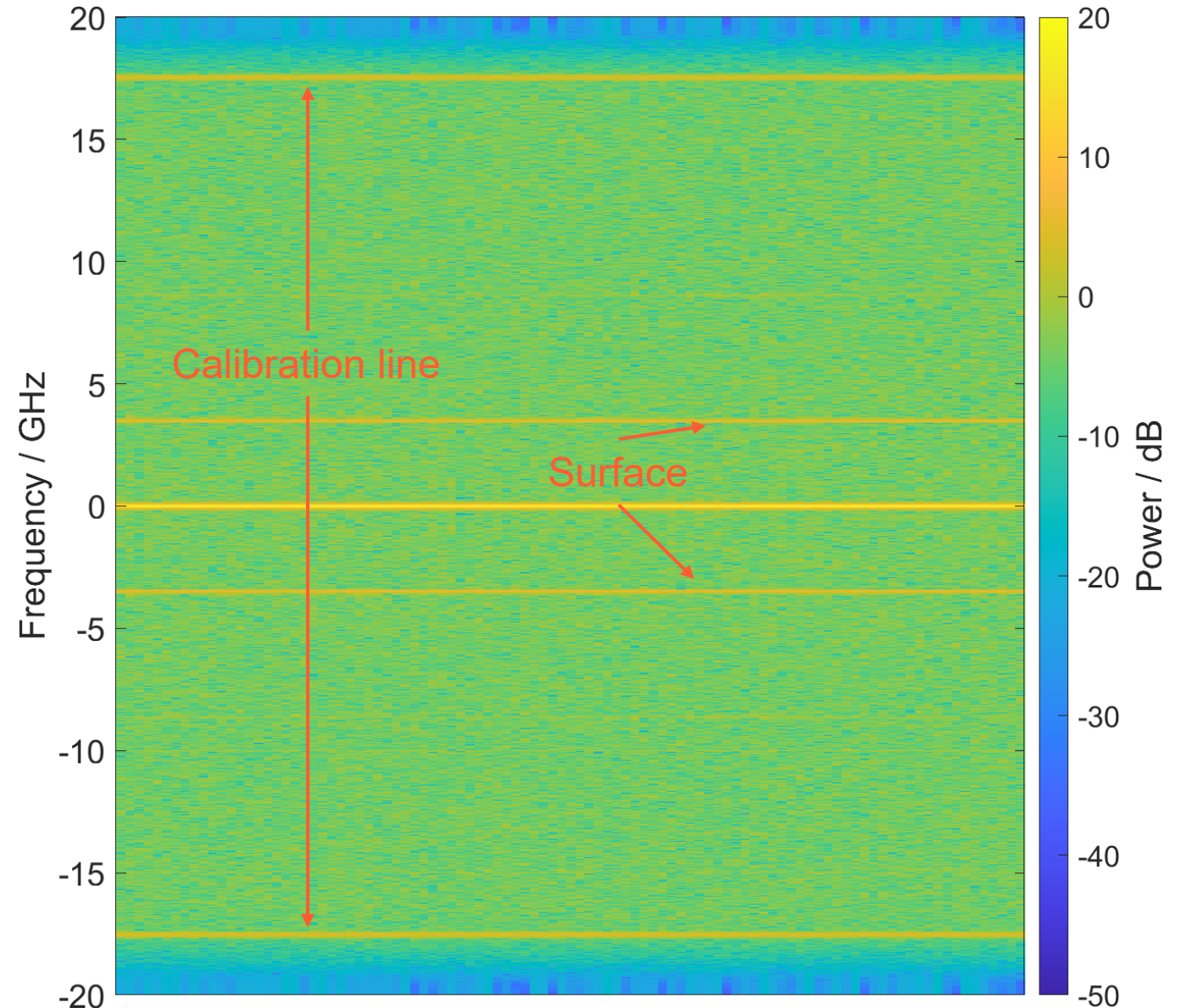


Static lab testing

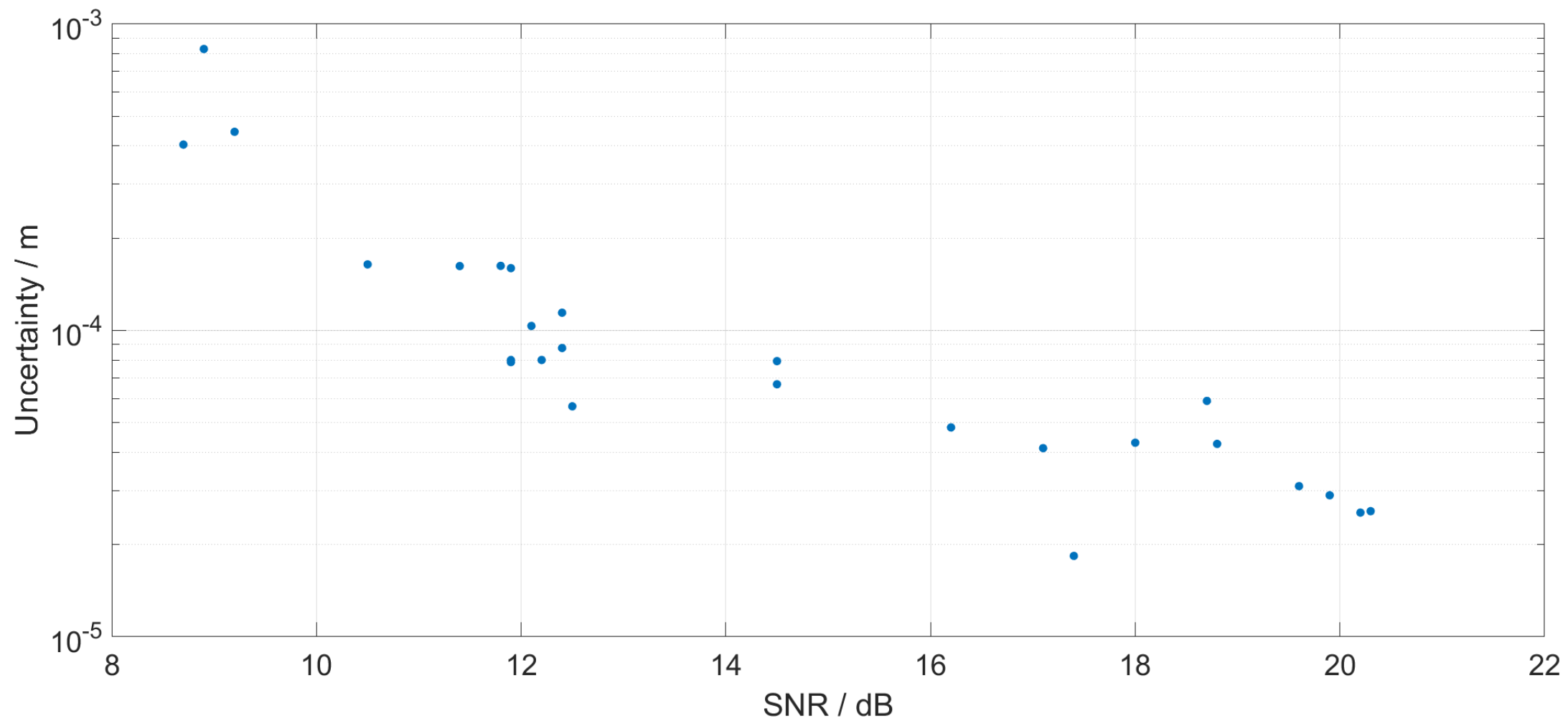
- Tested laser repetition rate
 - Small change in time between pulses would increase uncertainty if pulses not matched
 - With 1 pulse difference, no noticeable effects. Future testing will involve greater pulse difference or no pulse matching
- Polarisation dependence
 - Can control polarisation to increase SNR
 - Can also result in a decrease as the surface moves. Polarisation control not considered as hugely beneficial for now
- Time multiplexing
 - SMF and DCF components tested for a zero-dispersion delay module
 - ZDTDM required for time multiplexing for similar system sensitivities

Example static data

- Recorded 100 pulses to obtain mean and standard deviation of frequencies
- Use positive and negative frequencies out of FFT – easier when surface moves past 0 GHz balance point

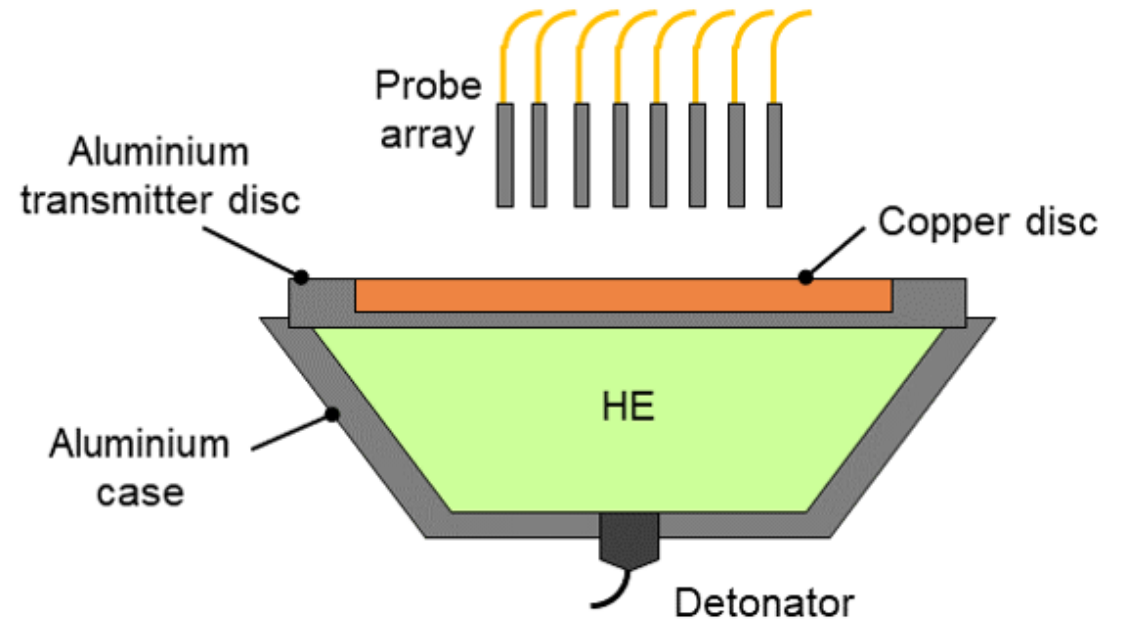


SNR

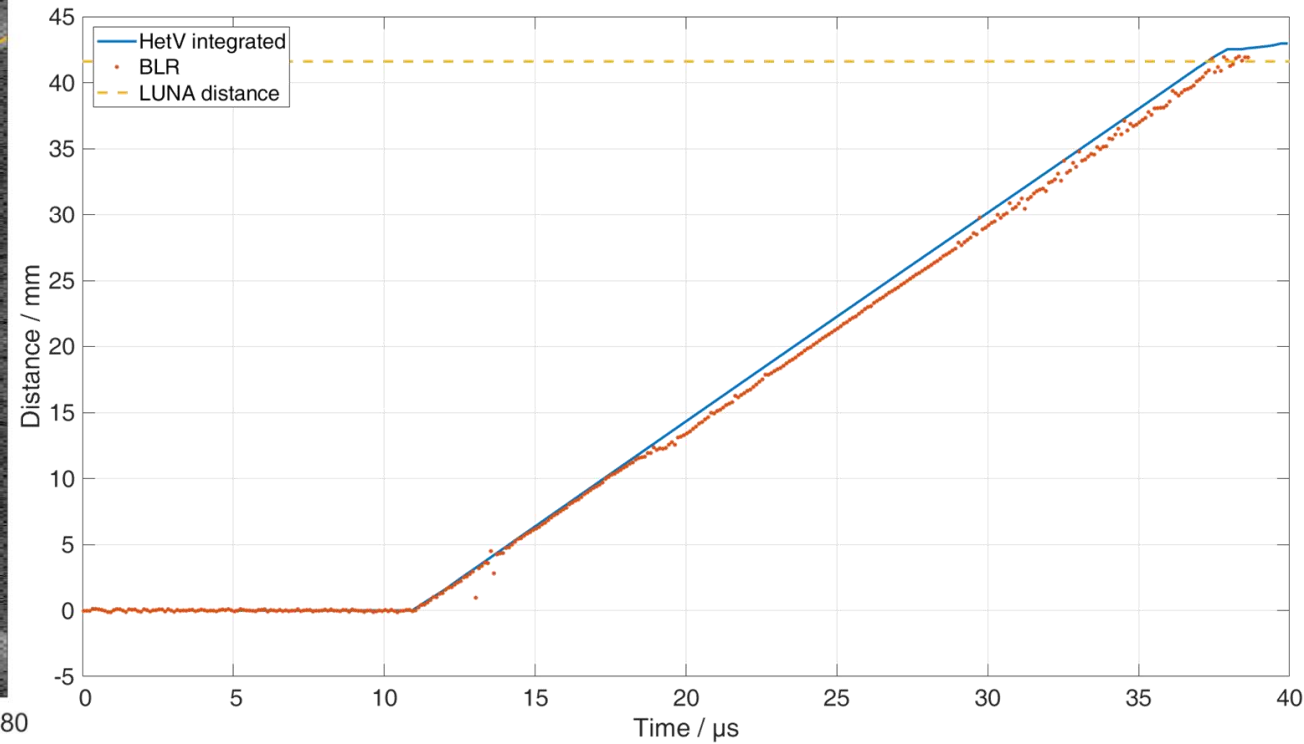
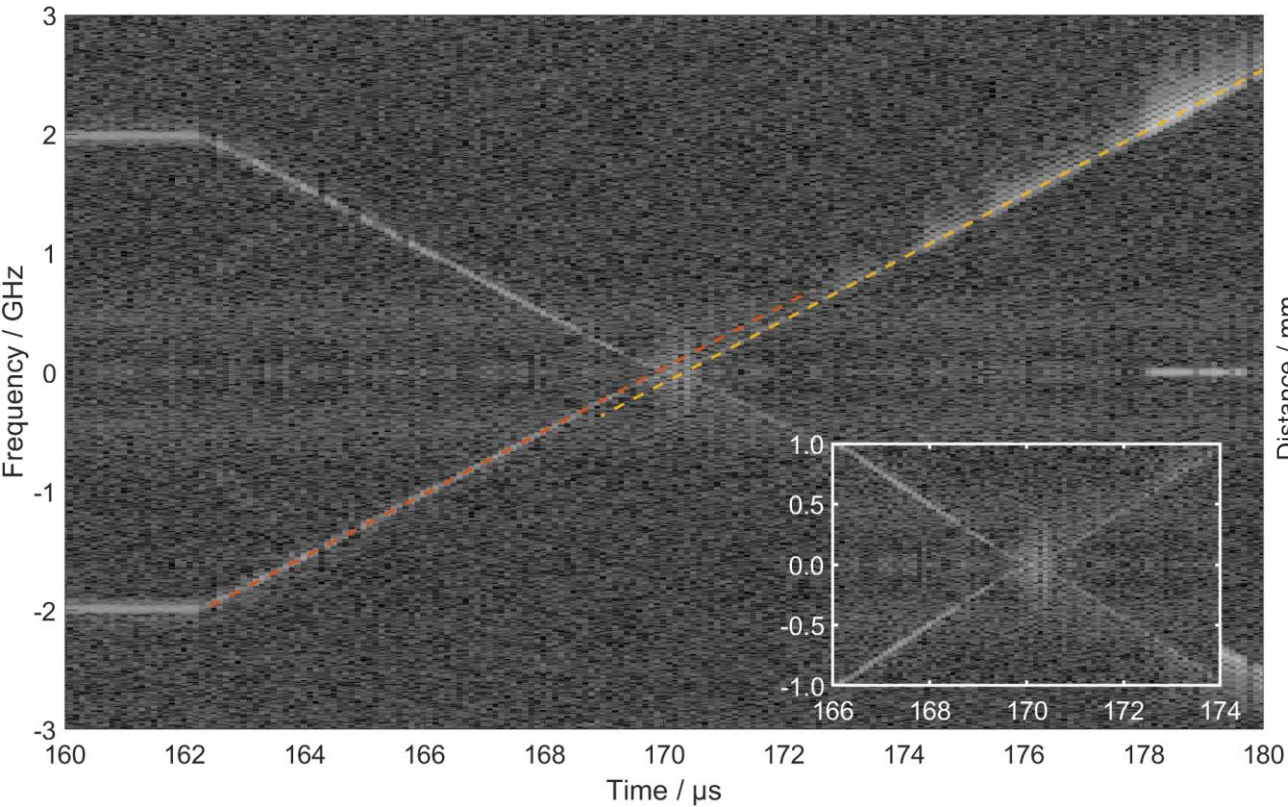


SURPOT 2

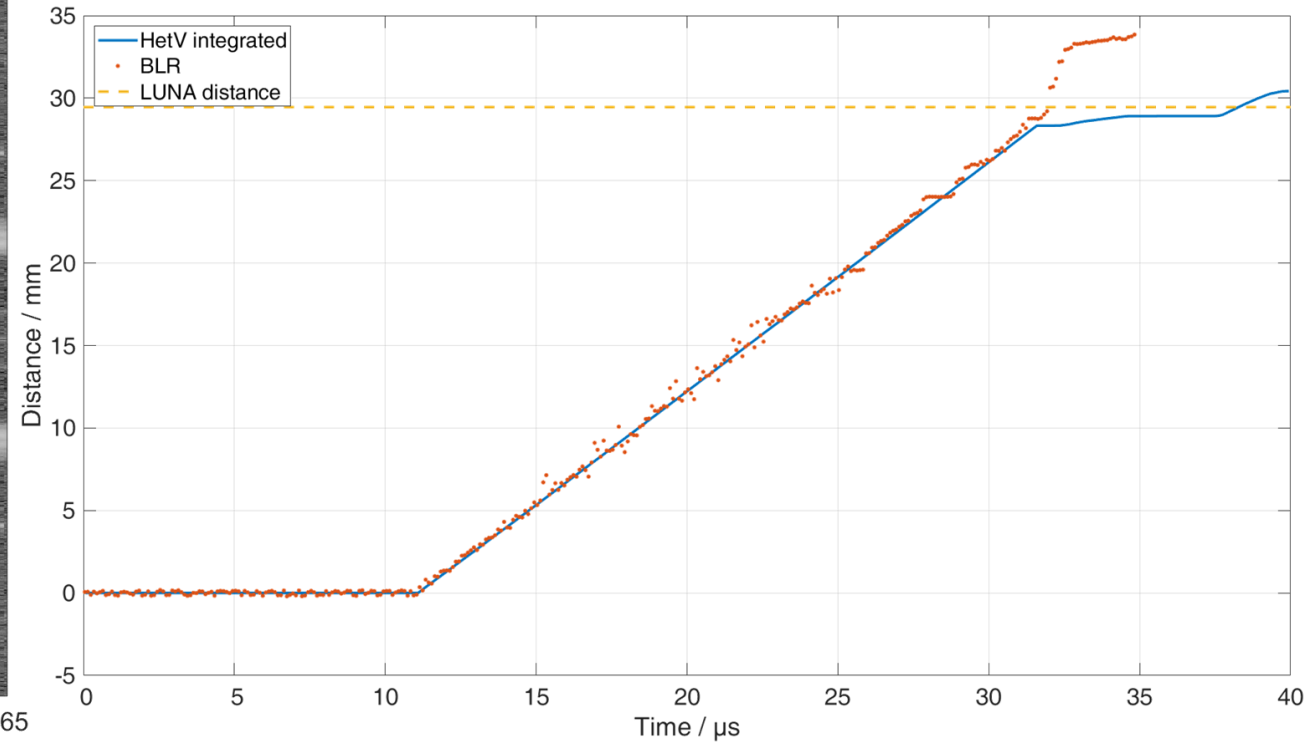
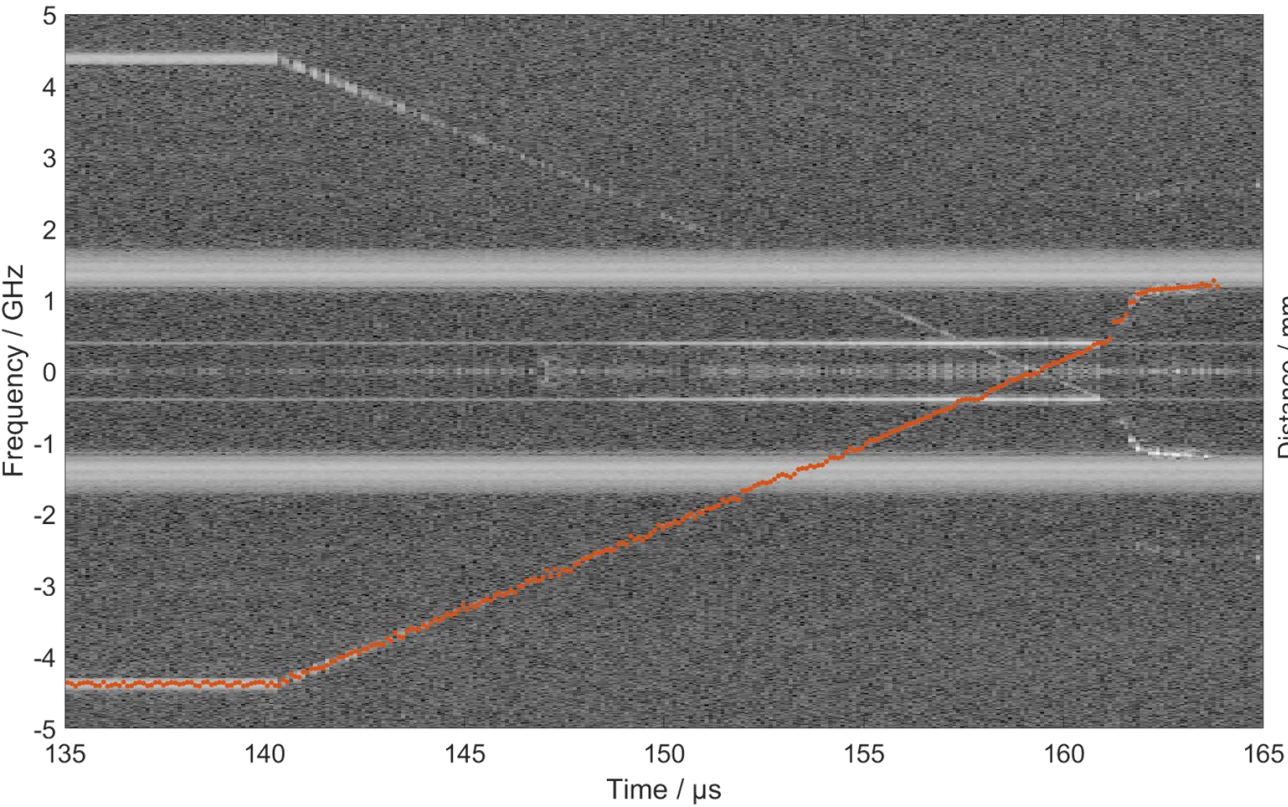
- Two channels of BLR fielded – first time fielded 2 channels at AWE. Multiplexed with HetV
- One channel was on a multipoint probe near centre
- Channel 2 was a discrete probe towards the edge



SURPOT 2 results – Channel 1

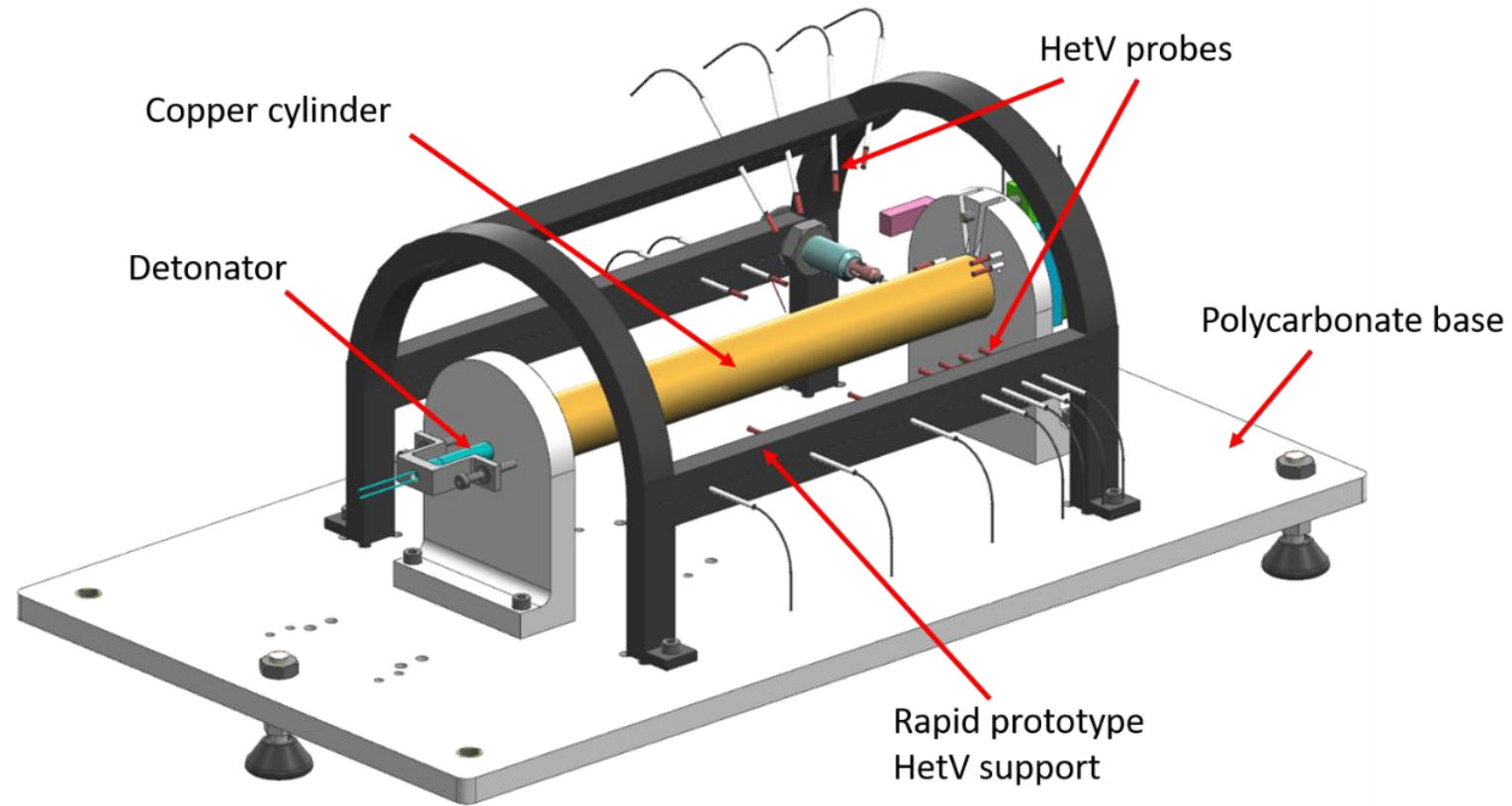


SURPOT 2 results – Channel 2

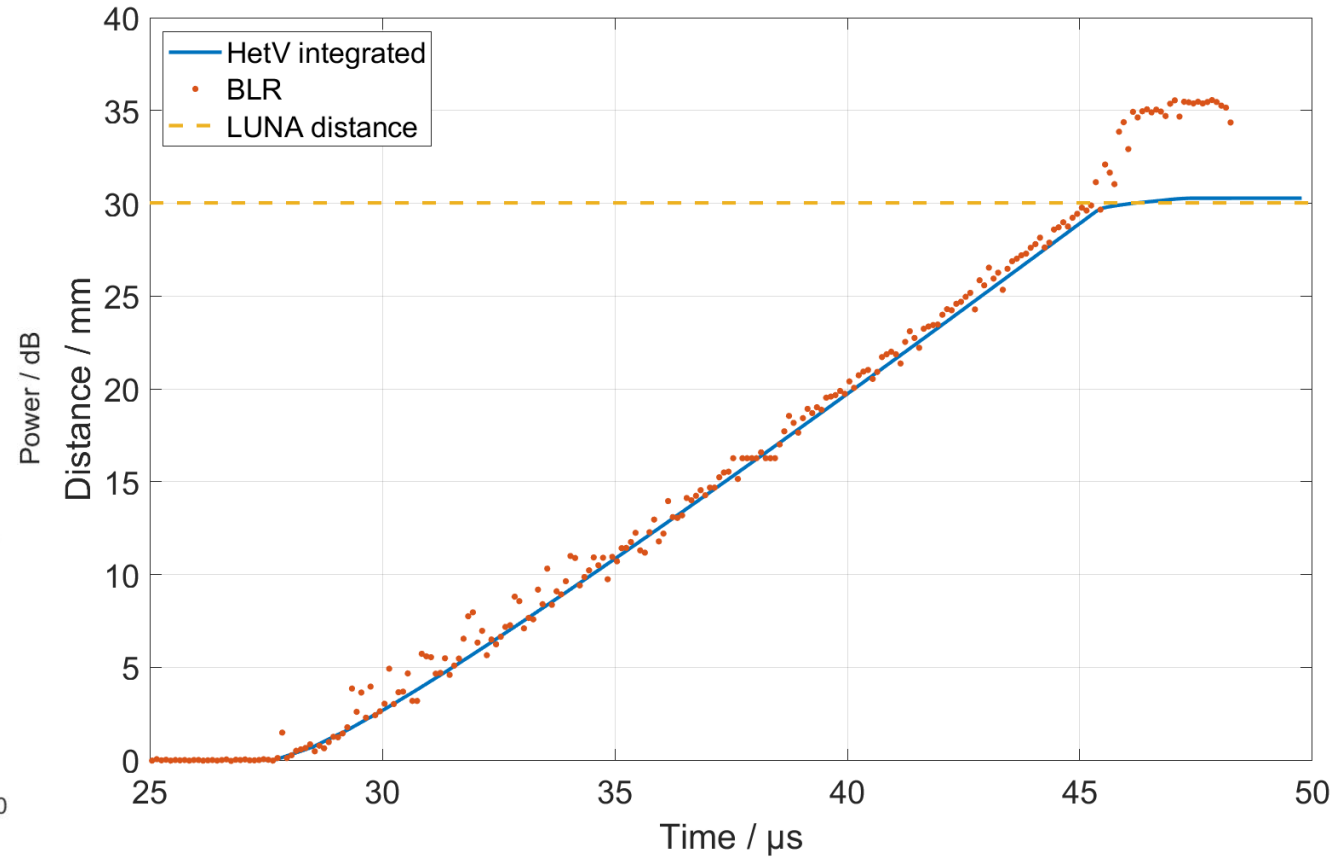
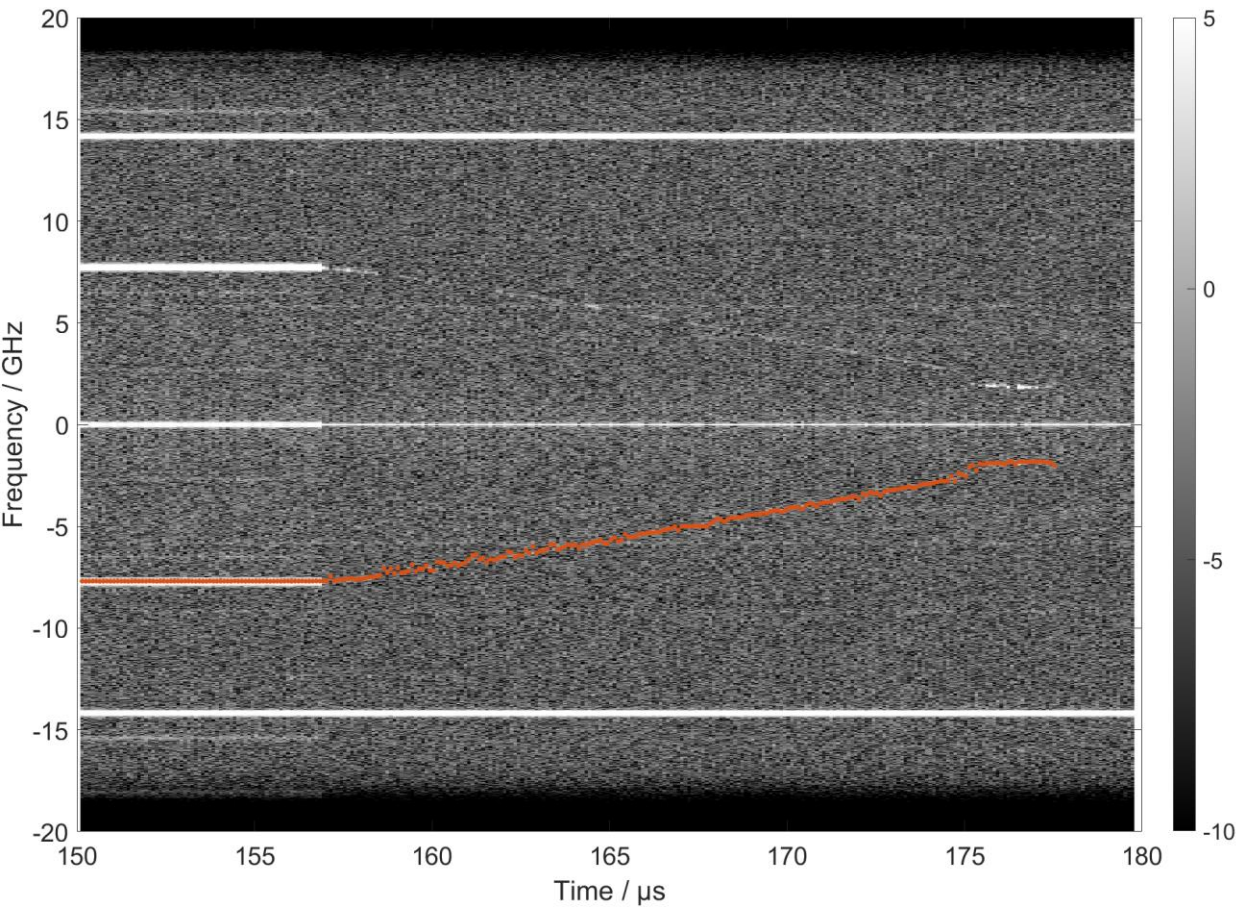


Cylinder test

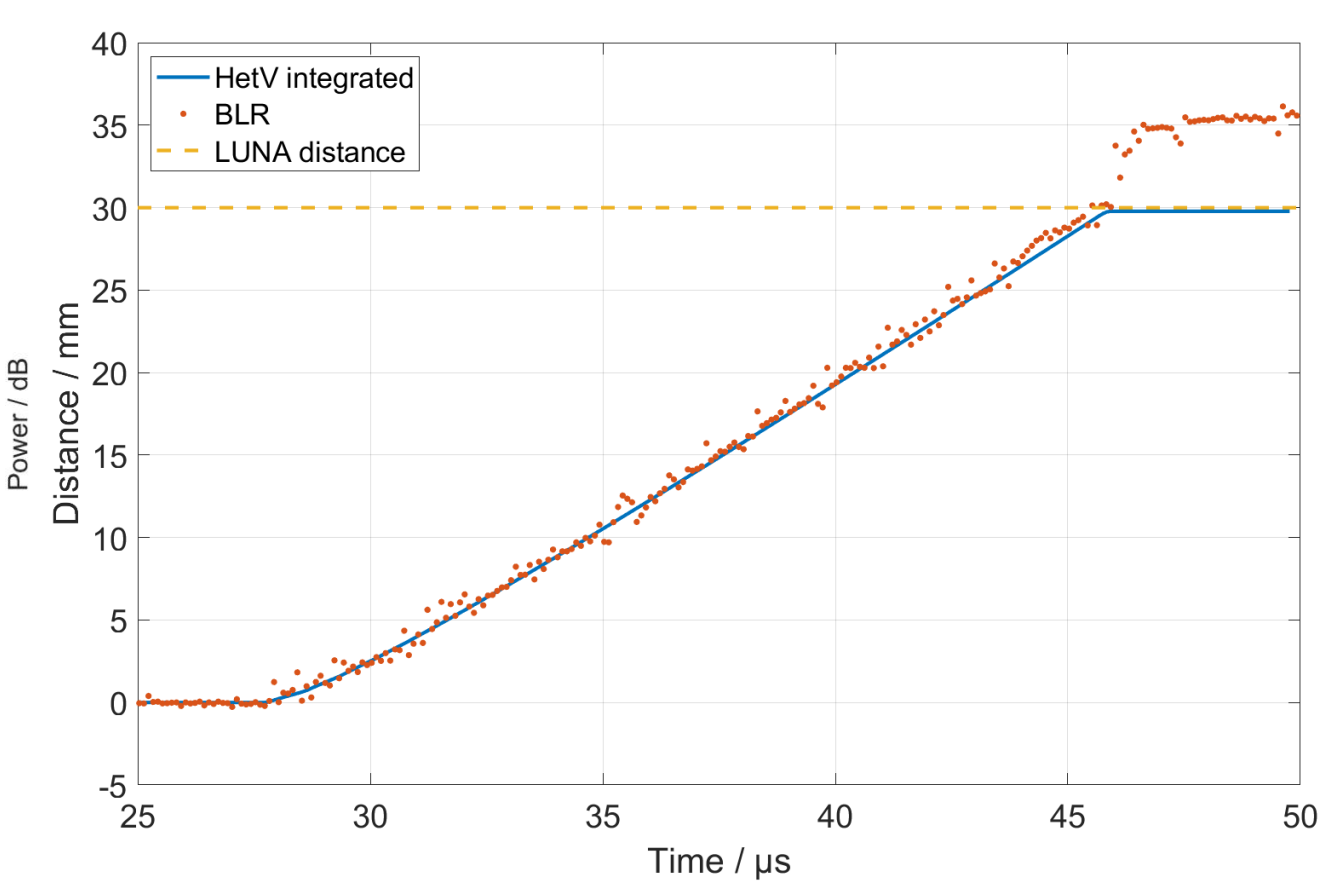
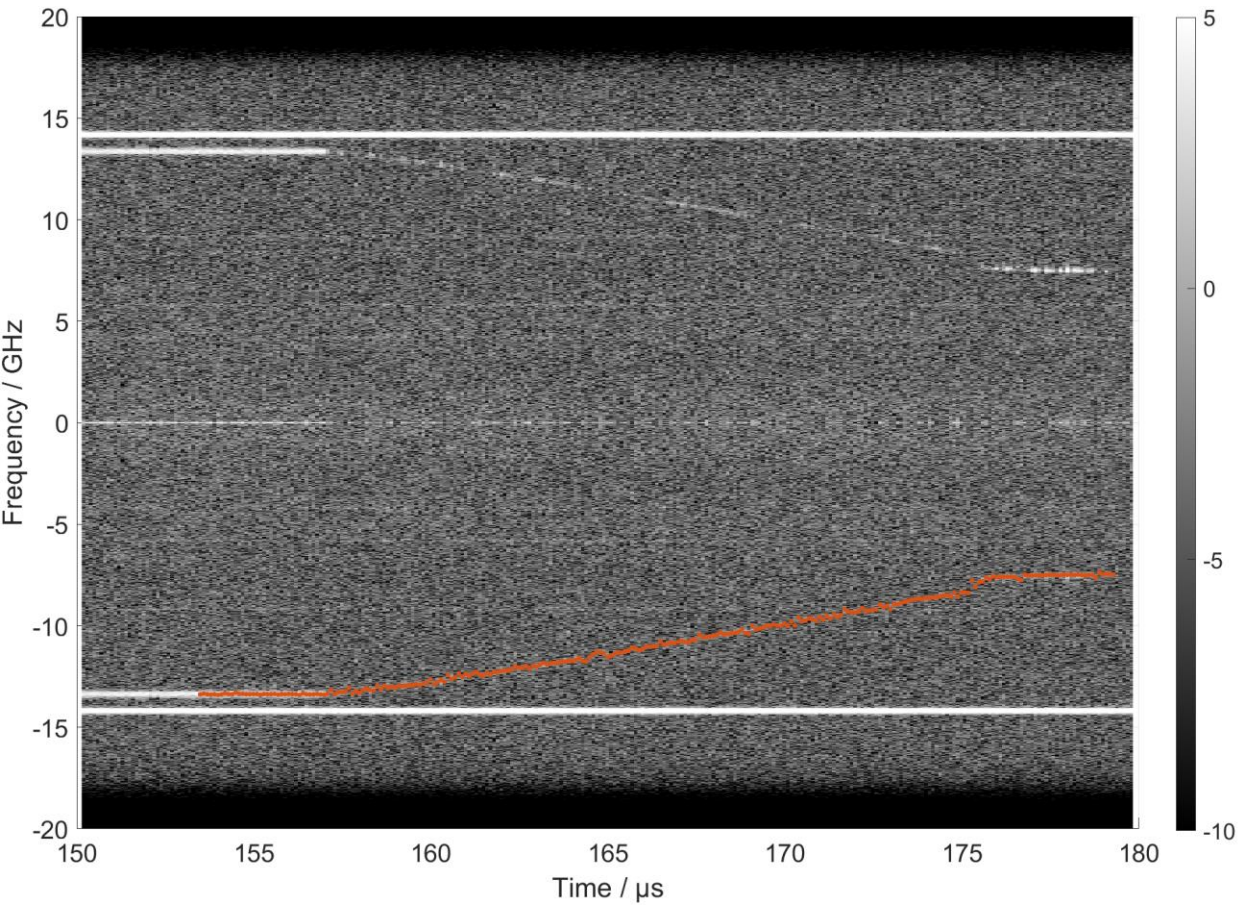
- One channel of BLR on two different tests. Multiplexed with HetV



Cylinder test 1 results

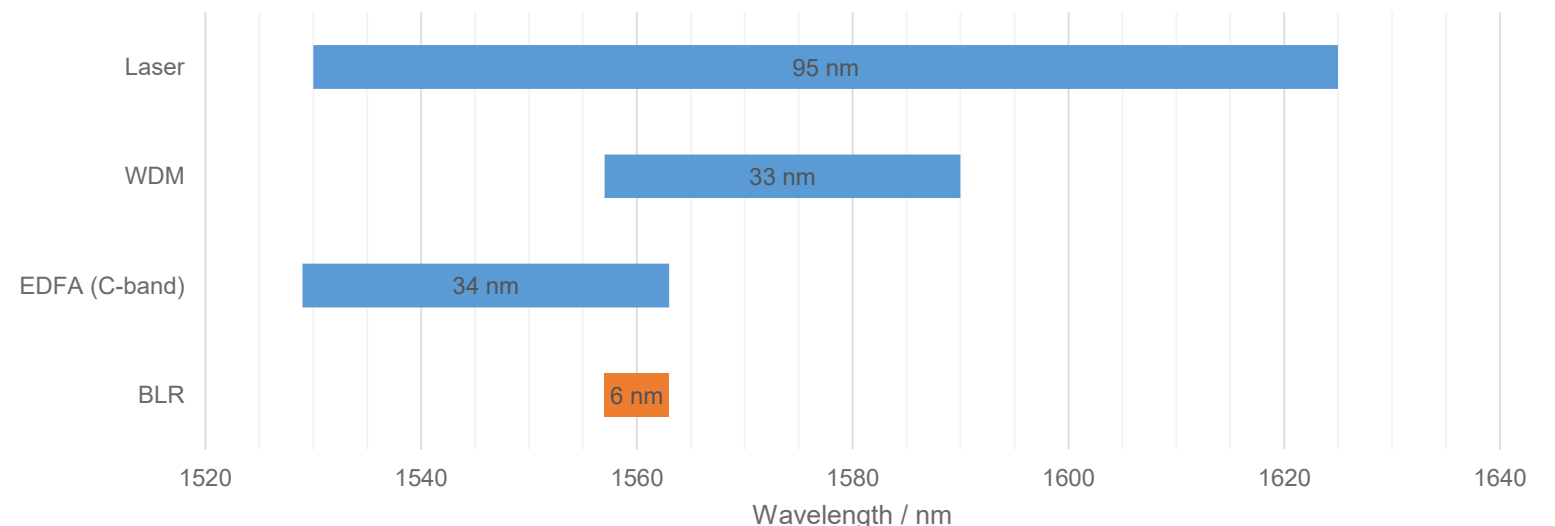


Cylinder test 2 results

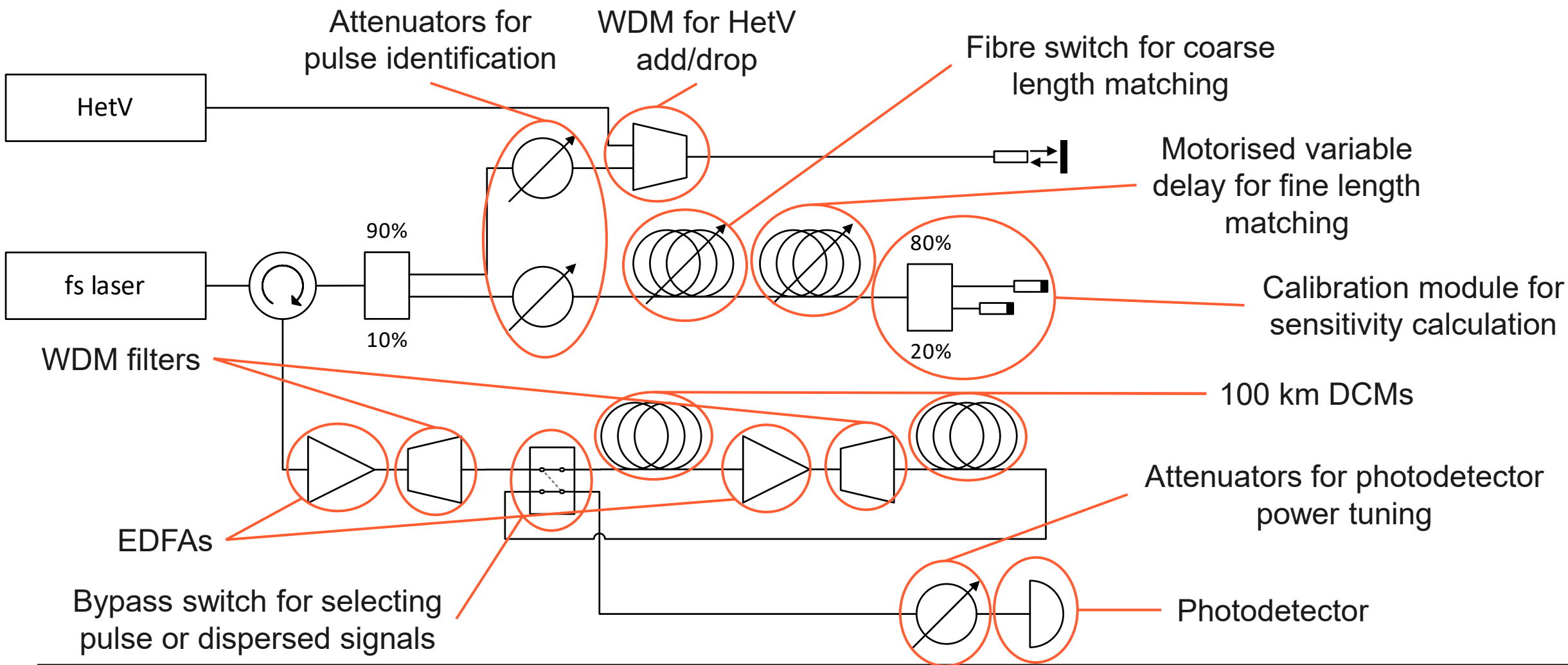


Required improvements

- View pulses without and with dispersion for setup
- Verify pulses seen are from probe / reflector
- Easier tuning for path length matching. Setup time is increased by finding / splicing fibres of correct lengths
- More light
- Parameter prediction
- Improved analysis software



System design



System parameters

- Parameter calculator application built
- Will use a 25 GHz oscilloscope
 - Can reduce DCM length down to 200 km
 - Can increase repetition rate from 10 MHz to 40 MHz

BLR Parameter Calculator

Settings

Start wavelength: 1557 nm End wavelength: 1563 nm

Laser bandwidth: 6 nm Estimated spatial resolution: 202.8 μ m

Digitiser bandwidth: 25 GHz Laser repetition rate: 10 MHz

Displacements: 0 mm (+) (-) DCM correction length: 240 km (+) (-)

25
50
100
150

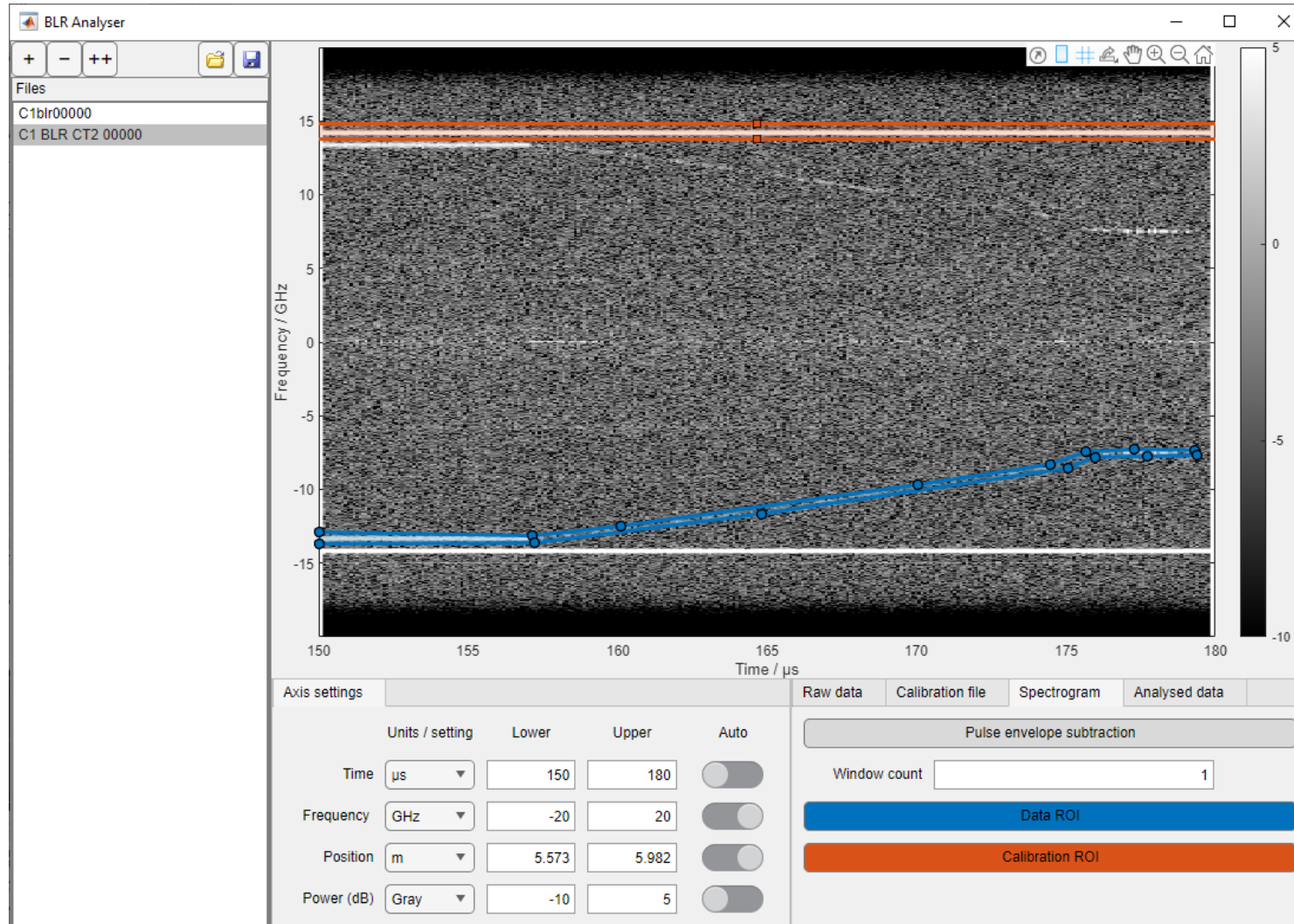
Parameters

| | 200 km | 240 km |
|-----------------------------|--------|--------|
| Delay time (μ s) | 111.11 | 133.33 |
| Sensitivity in air (mm/GHz) | 4.4402 | 5.3282 |
| Max distance in air (mm) | 111.01 | 133.2 |
| Max distance in fibre (mm) | 75.607 | 90.726 |
| Max difference in time (ns) | 0.3703 | 0.4443 |
| Temporal spread (ns) | 21.449 | 25.739 |
| Max repetition rate (MHz) | 45.066 | 37.555 |

Frequency change

| | 200 km | 240 km |
|--------|--------|--------|
| 0.5 mm | 0.1399 | 0.1166 |
| 1 mm | 0.2331 | 0.1943 |
| 2 mm | 0.4662 | 0.3885 |
| 5 mm | 1.1656 | 0.9713 |
| 10 mm | 2.3311 | 1.9426 |
| 20 mm | 4.6156 | 3.8463 |
| 25 mm | 5.7812 | 4.8176 |
| 50 mm | 11.516 | 9.5964 |
| 100 mm | 22.985 | 19.154 |
| 150 mm | 34.5 | 28.75 |

Analysis software



Summary

- Developed and demonstrated use of BLR in static lab testing and hydrodynamic experiments
- Easier and more reliable setup of BLR for trials
- Calculator for testing BLR parameters
- GUI for analysis and simple to use
- Future work to reduce uncertainty
 - Low noise amplification techniques – Raman amplifiers & SOAs
 - Software improvements – dechirping?